

TABLE OF CONTENTS

1	Introduction	5
2	State of the Art.....	6
2.1	Navigation's Key Elements: Localization, Mapping and Path Planning	6
2.2	Simultaneous Localization and Mapping Process	6
2.3	Iterative Closest Point Algorithm	9
3	Formulation of the Problem.....	11
4	Platform Development.....	12
5	Two Stage Leveled Map Accelerated 6DOF SLAM	14
5.1	Structure of the Implemented Method	14
5.2	Factorizing the Task: Leveled Data Sets Registration in 3DOF	15
5.3	Registration of the Pre-aligned 3D Data Set in 6DOF	18
5.4	Modifying the Implemented ICP Algorithm: Unique Matching of Model Points.....	18
6	Experiments.....	19
7	Discussion and Future Prospects	25
	References.....	28
	Author's Curriculum Vitae.....	29
	Abstract.....	30