

**1 Introduction**

1.1	Nonlinear Finite Elements in Design	1
1.2	Related Books and a Brief History of Nonlinear Finite Elements	4
1.3	Notation	7
1.3.1	<i>Indicial Notation</i>	7
1.3.2	<i>Tensor Notation</i>	8
1.3.3	<i>Functions</i>	8
1.3.4	<i>Matrix Notation</i>	8
1.4	Mesh Descriptions	9
1.5	Classification of Partial Differential Equations	13
1.6	Exercises	17

**2 Lagrangian and Eulerian Finite Elements in One Dimension**

2.1	Introduction	19
2.2	Governing Equations for Total Lagrangian Formulation	21
2.2.1	<i>Nomenclature</i>	21
2.2.2	<i>Motion and Strain Measure</i>	22
2.2.3	<i>Stress Measure</i>	22
2.2.4	<i>Governing Equations</i>	23
2.2.5	<i>Momentum Equation in Terms of Displacements</i>	26
2.2.6	<i>Continuity of Functions</i>	27
2.2.7	<i>Fundamental Theorem of Calculus</i>	28

		Outcomes
2.3	Weak Form for Total Lagrangian Formulation	28
2.3.1	<i>Strong Form to Weak Form</i>	28
2.3.2	<i>Weak Form to Strong Form</i>	30
2.3.3	<i>Physical Names of Virtual Work Terms</i>	32
2.3.4	<i>Principle of Virtual Work</i>	33
2.4	Finite Element Discretization in Total Lagrangian Formulation	34
2.4.1	<i>Finite Element Approximations</i>	34
2.4.2	<i>Nodal Forces</i>	35
2.4.3	<i>Semidiscrete Equations</i>	37
2.4.4	<i>Initial Conditions</i>	38
2.4.5	<i>Least-Square Fit to Initial Conditions</i>	39
2.4.6	<i>Diagonal Mass Matrix</i>	39
2.5	Element and Global Matrices	40
2.6	Governing Equations for Updated Lagrangian Formulation	51
2.6.1	<i>Boundary and Interior Continuity Conditions</i>	52
2.6.2	<i>Initial Conditions</i>	53
2.7	Weak Form for Updated Lagrangian Formulation	53
2.8	Element Equations for Updated Lagrangian Formulation	55
2.8.1	<i>Finite Element Approximation</i>	55
2.8.2	<i>Element Coordinates</i>	56
2.8.3	<i>Internal and External Nodal Forces</i>	58
2.8.4	<i>Mass Matrix</i>	59
2.8.5	<i>Equivalence of Updated and Total Lagrangian Formulations</i>	60
2.8.6	<i>Assembly, Boundary Conditions and Initial Conditions</i>	61
2.8.7	<i>Mesh Distortion</i>	64
2.9	Governing Equations for Eulerian Formulation	67
2.10	Weak Forms for Eulerian Mesh Equations	68
2.11	Finite Element Equations	69
2.11.1	<i>Momentum Equation</i>	71
2.12	Solution Methods	72
2.13	Summary	74
2.14	Exercises	75
<b>3</b>	<b>Continuum Mechanics</b>	<b>77</b>
3.1	Introduction	77
3.2	Deformation and Motion	78
3.2.1	<i>Definitions</i>	78
3.2.2	<i>Eulerian and Lagrangian Coordinates</i>	79
3.2.3	<i>Motion</i>	80
3.2.4	<i>Eulerian and Lagrangian Descriptions</i>	80
3.2.5	<i>Displacement, Velocity and Acceleration</i>	81
3.2.6	<i>Deformation Gradient</i>	83
3.2.7	<i>Conditions on Motion</i>	84
3.2.8	<i>Rigid Body Rotation and Coordinate Transformations</i>	85
3.3	Strain Measures	95
3.3.1	<i>Green Strain Tensor</i>	95
3.3.2	<i>Rate-of-Deformation</i>	97

<i>3.3.3 Rate-of-Deformation in Terms of Rate of Green Strain</i>	98
<b>3.4 Stress Measures</b>	104
<i>3.4.1 Definitions of Stresses</i>	104
<i>3.4.2 Transformation between Stresses</i>	105
<i>3.4.3 Corotational Stress and Rate-of-Deformation</i>	107
<b>3.5 Conservation Equations</b>	111
<i>3.5.1 Conservation Laws</i>	111
<i>3.5.2 Gauss's Theorem</i>	112
<i>3.5.3 Material Time Derivative of an Integral and Reynolds' Transport Theorem</i>	113
<i>3.5.4 Mass Conservation</i>	115
<i>3.5.5 Conservation of Linear Momentum</i>	116
<i>3.5.6 Equilibrium Equation</i>	119
<i>3.5.7 Reynolds' Theorem for a Density-Weighted Integrant</i>	119
<i>3.5.8 Conservation of Angular Momentum</i>	120
<i>3.5.9 Conservation of Energy</i>	120
<b>3.6 Lagrangian Conservation Equations</b>	123
<i>3.6.1 Introduction and Definitions</i>	123
<i>3.6.2 Conservation of Linear Momentum</i>	124
<i>3.6.3 Conservation of Angular Momentum</i>	126
<i>3.6.4 Conservation of Energy in Lagrangian Description</i>	127
<i>3.6.5 Power of PK2 Stress</i>	129
<b>3.7 Polar Decomposition and Frame-Invariance</b>	130
<i>3.7.1 Polar Decomposition Theorem</i>	130
<i>3.7.2 Objective Rates in Constitutive Equations</i>	135
<i>3.7.3 Jaumann Rate</i>	136
<i>3.7.4 Truesdell Rate and Green–Naghdi Rate</i>	137
<i>3.7.5 Explanation of Objective Rates</i>	142
<b>3.8 Exercises</b>	143

<b>4 Lagrangian Meshes</b>	147
<b>4.1 Introduction</b>	147
<b>4.2 Governing Equations</b>	148
<b>4.3 Weak Form: Principle of Virtual Power</b>	152
<i>4.3.1 Strong Form to Weak Form</i>	153
<i>4.3.2 Weak Form to Strong Form</i>	154
<i>4.3.3 Physical Names of Virtual Power Terms</i>	156
<b>4.4 Updated Lagrangian Finite Element Discretization</b>	158
<i>4.4.1 Finite Element Approximation</i>	158
<i>4.4.2 Internal and External Nodal Forces</i>	160
<i>4.4.3 Mass Matrix and Inertial Forces</i>	161
<i>4.4.4 Discrete Equations</i>	161
<i>4.4.5 Element Coordinates</i>	163
<i>4.4.6 Derivatives of Functions</i>	165
<i>4.4.7 Integration and Nodal Forces</i>	166
<i>4.4.8 Conditions on Parent to Current Map</i>	166
<i>4.4.9 Simplifications of Mass Matrix</i>	167

<b>4.5</b>	<b>Implementation</b>	<b>168</b>
4.5.1	<i>Indicial to Matrix Notation Translation</i>	169
4.5.2	<i>Voigt Notation</i>	171
4.5.3	<i>Numerical Quadrature</i>	173
4.5.4	<i>Selective-Reduced Integration</i>	174
4.5.5	<i>Element Force and Matrix Transformations</i>	175
<b>4.6</b>	<b>Corotational Formulations</b>	<b>194</b>
<b>4.7</b>	<b>Total Lagrangian Formulation</b>	<b>203</b>
4.7.1	<i>Governing Equations</i>	203
4.7.2	<i>Total Lagrangian Finite Element Equations by Transformation</i>	205
<b>4.8</b>	<b>Total Lagrangian Weak Form</b>	<b>206</b>
4.8.1	<i>Strong Form to Weak Form</i>	206
4.8.2	<i>Weak Form to Strong Form</i>	208
<b>4.9</b>	<b>Finite Element Semidiscretization</b>	<b>209</b>
4.9.1	<i>Discrete Equations</i>	209
4.9.2	<i>Implementation</i>	211
4.9.3	<i>Variational Principle for Large Deformation Statics</i>	221
<b>4.10</b>	<b>Exercises</b>	<b>225</b>
<b>5</b>	<b>Constitutive Models</b>	<b>227</b>
<b>5.1</b>	<b>Introduction</b>	<b>227</b>
<b>5.2</b>	<b>The Stress–Strain Curve</b>	<b>228</b>
5.2.1	<i>The Tensile Test</i>	229
<b>5.3</b>	<b>One-Dimensional Elasticity</b>	<b>233</b>
5.3.1	<i>Small Strains</i>	233
5.3.2	<i>Large Strains</i>	235
<b>5.4</b>	<b>Nonlinear Elasticity</b>	<b>237</b>
5.4.1	<i>Kirchhoff Material</i>	237
5.4.2	<i>Incompressibility</i>	241
5.4.3	<i>Kirchhoff Stress</i>	242
5.4.4	<i>Hypoelasticity</i>	242
5.4.5	<i>Relations between Tangent Moduli</i>	243
5.4.6	<i>Cauchy Elastic Material</i>	247
5.4.7	<i>Hyperelastic Materials</i>	248
5.4.8	<i>Elasticity Tensors</i>	249
5.4.9	<i>Isotropic Hyperelastic Materials</i>	251
5.4.10	<i>Neo-Hookean Material</i>	252
5.4.11	<i>Modified Mooney–Rivlin Material</i>	253
<b>5.5</b>	<b>One-Dimensional Plasticity</b>	<b>254</b>
5.5.1	<i>Rate-Independent Plasticity in One Dimension</i>	254
5.5.2	<i>Extension to Kinematic Hardening</i>	257
5.5.3	<i>Rate-Dependent Plasticity in One Dimension</i>	260
<b>5.6</b>	<b>Multiaxial Plasticity</b>	<b>262</b>
5.6.1	<i>Hypoelastic-Plastic Materials</i>	263
5.6.2	<i>J<sub>2</sub> Flow Theory Plasticity</i>	267
5.6.3	<i>Extension to Kinematic Hardening</i>	269
5.6.4	<i>Mohr–Coulomb Constitutive Model</i>	271

5.6.5	<i>Drucker–Prager Constitutive Model</i>	273
5.6.6	<i>Porous Elastic–Plastic Solids: Gurson Model</i>	274
5.6.7	<i>Corotational Stress Formulation</i>	277
5.6.8	<i>Small-Strain Formulation</i>	279
5.6.9	<i>Large-Strain Viscoplasticity</i>	280
5.7	<b>Hyperelastic–Plastic Models</b>	281
5.7.1	<i>Multiplicative Decomposition of Deformation Gradient</i>	282
5.7.2	<i>Hyperelastic Potential and Stress</i>	283
5.7.3	<i>Decomposition of Rates of Deformation</i>	283
5.7.4	<i>Flow Rule</i>	285
5.7.5	<i>Tangent Moduli</i>	286
5.7.6	<i><math>J_2</math> Flow Theory</i>	288
5.7.7	<i>Implications for Numerical Treatment of Large Rotations</i>	291
5.7.8	<i>Single-Crystal Plasticity</i>	291
5.8	<b>Viscoelasticity</b>	292
5.8.1	<i>Small Strains</i>	292
5.8.2	<i>Finite Strain Viscoelasticity</i>	293
5.9	<b>Stress Update Algorithms</b>	294
5.9.1	<i>Return Mapping Algorithms for Rate-Independent Plasticity</i>	295
5.9.2	<i>Fully Implicit Backward Euler Scheme</i>	296
5.9.3	<i>Application to <math>J_2</math> Flow Theory – Radial Return Algorithm</i>	300
5.9.4	<i>Algorithmic Moduli</i>	302
5.9.5	<i>Algorithmic Moduli: <math>J_2</math> Flow and Radial Return</i>	305
5.9.6	<i>Semi-Implicit Backward Euler Scheme</i>	306
5.9.7	<i>Algorithmic Moduli – Semi-Implicit Scheme</i>	307
5.9.8	<i>Return Mapping Algorithms for Rate-Dependent Plasticity</i>	308
5.9.9	<i>Rate Tangent Modulus Method</i>	310
5.9.10	<i>Incrementally Objective Integration Schemes for Large Deformations</i>	311
5.9.11	<i>Semi-Implicit Scheme for Hyperelastic–Plastic Constitutive Models</i>	312
5.10	<b>Continuum Mechanics and Constitutive Models</b>	314
5.10.1	<i>Eulerian, Lagrangian and Two-Point Tensors</i>	314
5.10.2	<i>Pull-Back, Push-Forward and the Lie Derivative</i>	314
5.10.3	<i>Material Frame Indifference</i>	319
5.10.4	<i>Implications for Constitutive Relations</i>	321
5.10.5	<i>Objective Scalar Functions</i>	322
5.10.6	<i>Restrictions on Elastic Moduli</i>	323
5.10.7	<i>Material Symmetry</i>	324
5.10.8	<i>Frame Invariance in Hyperelastic–Plastic Models</i>	325
5.10.9	<i>Clausius–Duhem Inequality and Stability Postulates</i>	326
5.11	<b>Exercises</b>	328
<b>6</b>	<b>Solution Methods and Stability</b>	<b>329</b>
6.1	<b>Introduction</b>	329
6.2	<b>Explicit Methods</b>	330
6.2.1	<i>Central Difference Method</i>	330
6.2.2	<i>Implementation</i>	332
6.2.3	<i>Energy Balance</i>	335

6.2.4	<i>Accuracy</i>	336
6.2.5	<i>Mass Scaling, Subcycling and Dynamic Relaxation</i>	337
6.3	<b>Equilibrium Solutions and Implicit Time Integration</b>	337
6.3.1	<i>Equilibrium and Transient Problems</i>	337
6.3.2	<i>Equilibrium Solutions and Equilibrium Points</i>	338
6.3.3	<i>Newmark <math>\beta</math>-Equations</i>	338
6.3.4	<i>Newton's Method</i>	339
6.3.5	<i>Newton's Method for n Unknowns</i>	341
6.3.6	<i>Conservative Problems</i>	343
6.3.7	<i>Implementation of Newton's Method</i>	344
6.3.8	<i>Constraints</i>	346
6.3.9	<i>Convergence Criteria</i>	353
6.3.10	<i>Line Search</i>	354
6.3.11	<i>The <math>\alpha</math>-Method</i>	355
6.3.12	<i>Accuracy and Stability of Implicit Methods</i>	356
6.3.13	<i>Convergence and Robustness of Newton Iteration</i>	357
6.3.14	<i>Selection of Integration Method</i>	358
6.4	<b>Linearization</b>	358
6.4.1	<i>Linearization of the Internal Nodal Forces</i>	358
6.4.2	<i>Material Tangent Stiffness</i>	360
6.4.3	<i>Geometric Stiffness</i>	361
6.4.4	<i>Alternative Derivations of Tangent Stiffness</i>	362
6.4.5	<i>External Load Stiffness</i>	364
6.4.6	<i>Directional Derivatives</i>	372
6.4.7	<i>Algorithmically Consistent Tangent Stiffness</i>	374
6.5	<b>Stability and Continuation Methods</b>	375
6.5.1	<i>Stability</i>	375
6.5.2	<i>Branches of Equilibrium Solutions</i>	378
6.5.3	<i>Methods of Continuation and Arc Length Methods</i>	380
6.5.4	<i>Linear Stability</i>	382
6.5.5	<i>Symmetric Systems</i>	383
6.5.6	<i>Conservative Systems</i>	384
6.5.7	<i>Remarks on Linear Stability Analysis</i>	384
6.5.8	<i>Estimates of Critical Points</i>	385
6.5.9	<i>Initial Estimates of Critical Points</i>	386
6.6	<b>Numerical Stability</b>	391
6.6.1	<i>Definition and Discussion</i>	391
6.6.2	<i>Stability of a Model Linear System: Heat Conduction</i>	392
6.6.3	<i>Amplification Matrices</i>	396
6.6.4	<i>Amplification Matrix for Generalized Trapezoidal Rule</i>	397
6.6.5	<i>The z-Transform</i>	398
6.6.6	<i>Stability of Damped Central Difference Method</i>	399
6.6.7	<i>Linearized Stability Analysis of Newmark <math>\beta</math>-Method</i>	401
6.6.8	<i>Eigenvalue Inequality and Time Step Estimates</i>	403
6.6.9	<i>Element Eigenvalues</i>	404
6.6.10	<i>Stability in Energy</i>	406

6.7	Material Stability	407
6.7.1	Description and Early Work	407
6.7.2	Material Stability Analysis	408
6.7.3	Material Instability and Change of Type of PDEs in 1D	411
6.7.4	Regularization	412
6.8	Exercises	415
<b>7</b>	<b>Arbitrary Lagrangian Eulerian Formulations</b>	<b>417</b>
7.1	Introduction	417
7.2	ALE Continuum Mechanics	419
7.2.1	Material Motion, Mesh Displacement, Mesh Velocity, and Mesh Acceleration	419
7.2.2	Material Time Derivative and Convective Velocity	421
7.2.3	Relationship of ALE Description to Eulerian and Lagrangian Descriptions	422
7.3	Conservation Laws in ALE Description	426
7.3.1	Conservation of Mass (Equation of Continuity)	426
7.3.2	Conservation of Linear and Angular Momenta	427
7.3.3	Conservation of Energy	428
7.4	ALE Governing Equations	428
7.5	Weak Forms	429
7.5.1	Continuity Equation – Weak Form	430
7.5.2	Momentum Equation – Weak Form	430
7.5.3	Finite Element Approximations	430
7.5.4	The Finite Element Matrix Equations	432
7.6	Introduction to the Petrov–Galerkin Method	433
7.6.1	Galerkin Discretization of the Advection–Diffusion Equation	434
7.6.2	Petrov–Galerkin Stabilization	436
7.6.3	Alternative Derivation of the SUPG	437
7.6.4	Parameter Determination	438
7.6.5	SUPG Multiple Dimensions	441
7.7	Petrov–Galerkin Formulation of Momentum Equation	442
7.7.1	Alternative Stabilization Formulation	443
7.7.2	The $\delta v_i^{\text{PG}}$ Test Function	443
7.7.3	Finite Element Equation	444
7.8	Path-Dependent Materials	445
7.8.1	Strong Form of Stress Update	446
7.8.2	Weak Form of Stress Update	446
7.8.3	Finite Element Discretization	446
7.8.4	Stress Update Procedures	447
7.8.5	Finite Element Implementation of Stress Update Procedures in 1D	453
7.8.6	Explicit Time Integration Algorithm	456
7.9	Linearization of the Discrete Equations	457
7.9.1	Internal Nodal Forces	457
7.9.2	External Nodal Forces	459

7.10	Mesh Update Equations	460
7.10.1	Introduction	460
7.10.2	Mesh Motion Prescribed A Priori	461
7.10.3	Lagrange–Euler Matrix Method	461
7.10.4	Deformation Gradient Formulations	463
7.10.5	Automatic Mesh Generation	465
7.10.6	Mesh Update Using a Modified Elasticity Equation	466
7.10.7	Mesh Update Example	467
7.11	Numerical Example: An Elastic–Plastic Wave Propagation Problem	468
7.12	Total ALE Formulations	471
7.12.1	Total ALE Conservation Laws	471
7.12.2	Reduction to Updated ALE Conservation Laws	473
7.13	Exercises	475
8	<b>Element Technology</b>	477
8.1	Introduction	477
8.2	Element Performance	479
8.2.1	Overview	479
8.2.2	Completeness, Consistency, and Reproducing Conditions	483
8.2.3	Convergence Results for Linear Problems	484
8.2.4	Convergence in Nonlinear Problems	486
8.3	Element Properties and Patch Tests	487
8.3.1	Patch Tests	487
8.3.2	Standard Patch Test	487
8.3.3	Patch Test in Nonlinear Programs	489
8.3.4	Patch Test in Explicit Programs	489
8.3.5	Patch Tests for Stability	490
8.3.6	Linear Reproducing Conditions of Isoparametric Elements	490
8.3.7	Completeness of Subparametric and Superparametric Elements	492
8.3.8	Element Rank and Rank Deficiency	493
8.3.9	Rank of Numerically Integrated Elements	494
8.4	Q4 and Volumetric Locking	496
8.4.1	Element Description	496
8.4.2	Basis Form of Q4 Approximation	497
8.4.3	Locking in Q4	499
8.5	Multi-Field Weak Forms and Elements	501
8.5.1	Nomenclature	501
8.5.2	Hu–Washizu Weak Form	501
8.5.3	Alternative Multi-Field Weak Forms	503
8.5.4	Total Lagrangian Form of the Hu–Washizu	504
8.5.5	Pressure–Velocity (p–v) Implementation	505
8.5.6	Element Specific Pressure	507
8.5.7	Finite Element Implementation of Hu–Washizu	508
8.5.8	Simo–Hughes B-Bar Method	510
8.5.9	Simo–Rifai Formulation	511
8.6	Multi-Field Quadrilaterals	514

8.6.1	<i>Assumed Velocity Strain to Avoid Volumetric Locking</i>	514
8.6.2	<i>Shear Locking and its Elimination</i>	516
8.6.3	<i>Stiffness Matrices for Assumed Strain Elements</i>	517
8.6.4	<i>Other Techniques in Quadrilaterals</i>	517
8.7	<b>One-Point Quadrature Elements</b>	518
8.7.1	<i>Nodal Forces and B-Matrix</i>	518
8.7.2	<i>Spurious Singular Modes (Hourglass)</i>	519
8.7.3	<i>Perturbation Hourglass Stabilization</i>	521
8.7.4	<i>Stabilization Procedure</i>	522
8.7.5	<i>Scaling and Remarks</i>	522
8.7.6	<i>Physical Stabilization</i>	523
8.7.7	<i>Assumed Strain with Multiple Integration Points</i>	525
8.7.8	<i>Three-Dimensional Elements</i>	526
8.8	<b>Examples</b>	527
8.8.1	<i>Static Problems</i>	527
8.8.2	<i>Dynamic Cantilever Beam</i>	528
8.8.3	<i>Cylindrical Stress Wave</i>	530
8.9	<b>Stability</b>	531
8.10	<b>Exercises</b>	533
<b>9</b>	<b>Beams and Shells</b>	<b>535</b>
9.1	<b>Introduction</b>	535
9.2	<b>Beam Theories</b>	537
9.2.1	<i>Assumptions of Beam Theories</i>	537
9.2.2	<i>Timoshenko (Shear Beam) Theory</i>	538
9.2.3	<i>Euler–Bernoulli Theory</i>	539
9.2.4	<i>Discrete Kirchhoff and Mindlin–Reissner Theories</i>	540
9.3	<b>Continuum-Based Beam</b>	540
9.3.1	<i>Definitions and Nomenclature</i>	541
9.3.2	<i>Assumptions</i>	542
9.3.3	<i>Motion</i>	543
9.3.4	<i>Nodal Forces</i>	545
9.3.5	<i>Constitutive Update</i>	545
9.3.6	<i>Continuum Nodal Internal Forces</i>	547
9.3.7	<i>Mass Matrix</i>	549
9.3.8	<i>Equations of Motion</i>	550
9.3.9	<i>Tangent Stiffness</i>	550
9.4	<b>Analysis of the CB Beam</b>	551
9.4.1	<i>Motion</i>	551
9.4.2	<i>Velocity Strains</i>	554
9.4.3	<i>Resultant Stresses and Internal Power</i>	555
9.4.4	<i>Resultant External Forces</i>	556
9.4.5	<i>Boundary Conditions</i>	557
9.4.6	<i>Weak Form</i>	558
9.4.7	<i>Strong Form</i>	558
9.4.8	<i>Finite Element Approximation</i>	559

<b>9.5</b>	<b>Continuum-Based Shell Implementation</b>	<b>563</b>
9.5.1	<i>Assumptions in Classical Shell Theories</i>	564
9.5.2	<i>Coordinates and Definitions</i>	564
9.5.3	<i>Assumptions</i>	565
9.5.4	<i>Coordinate Systems</i>	565
9.5.5	<i>Finite Element Approximation of Motion</i>	566
9.5.6	<i>Local Coordinates</i>	568
9.5.7	<i>Constitutive Equation</i>	569
9.5.8	<i>Thickness</i>	570
9.5.9	<i>Master Nodal Forces</i>	570
9.5.10	<i>Mass Matrix</i>	571
9.5.11	<i>Discrete Momentum Equation</i>	571
9.5.12	<i>Tangent Stiffness</i>	572
9.5.13	<i>Five Degree-of-Freedom Formulation</i>	572
9.5.14	<i>Large Rotations</i>	573
9.5.15	<i>Euler's Theorem</i>	573
9.5.16	<i>Exponential Map</i>	575
9.5.17	<i>First- and Second-Order Updates</i>	576
9.5.18	<i>Hughes–Winget Update</i>	577
9.5.19	<i>Quaternions</i>	577
9.5.20	<i>Implementation</i>	578
<b>9.6</b>	<b>CB Shell Theory</b>	<b>578</b>
9.6.1	<i>Motion</i>	578
9.6.2	<i>Velocity Strains</i>	580
9.6.3	<i>Resultant Stresses</i>	581
9.6.4	<i>Boundary Conditions</i>	582
9.6.5	<i>Inconsistencies and Idiosyncrasies of Structural Theories</i>	583
<b>9.7</b>	<b>Shear and Membrane Locking</b>	<b>584</b>
9.7.1	<i>Description and Definitions</i>	584
9.7.2	<i>Shear Locking</i>	585
9.7.3	<i>Membrane Locking</i>	587
9.7.4	<i>Elimination of Locking</i>	588
<b>9.8</b>	<b>Assumed Strain Elements</b>	<b>589</b>
9.8.1	<i>Assumed Strain 4-Node Quadrilateral</i>	589
9.8.2	<i>Rank of Element</i>	591
9.8.3	<i>Nine-Node Quadrilateral</i>	591
<b>9.9</b>	<b>One-Point Quadrature Elements</b>	<b>592</b>
<b>9.10</b>	<b>Exercises</b>	<b>595</b>
<b>10</b>	<b>Contact-Impact</b>	<b>597</b>
10.1	<i>Introduction</i>	597
10.2	<i>Contact Interface Equations</i>	598
10.2.1	<i>Notation and Preliminaries</i>	598
10.2.2	<i>Impenetrability Condition</i>	600
10.2.3	<i>Traction Conditions</i>	602
10.2.4	<i>Unitary Contact Condition</i>	603

10.2.5	<i>Surface Description</i>	11.4.3	603
10.2.6	<i>Interpenetration Measure</i>	11.4.11	604
10.2.7	<i>Path-Independent Interpenetration Rate</i>	12.1	605
10.2.8	<i>Tangential Relative Velocity for Interpenetrated Bodies</i>	14.6	606
10.3	<b>Friction Models</b>	11.6.1	609
10.3.1	<i>Classification</i>	11.6.1	609
10.3.2	<i>Coulomb Friction</i>	11.5.11	609
10.3.3	<i>Interface Constitutive Equations</i>	12.5.11	610
10.4	<b>Weak Forms</b>	11.4.1	614
10.4.1	<i>Notation and Preliminaries</i>	8.1	614
10.4.2	<i>Lagrange Multiplier Weak Form</i>	11.8.11	615
10.4.3	<i>Contribution of Virtual Power to Contact Surface</i>	12.8.11	617
10.4.4	<i>Rate-Dependent Penalty</i>	11.9.11	618
10.4.5	<i>Interpenetration-Dependent Penalty</i>	11.9.11	620
10.4.6	<i>Perturbed Lagrangian Weak Form</i>	12.9.11	620
10.4.7	<i>Augmented Lagrangian</i>	10.1	621
10.4.8	<i>Tangential Tractions by Lagrange Multipliers</i>	11.11	622
10.5	<b>Finite Element Discretization</b>	11.2.4	624
10.5.1	<i>Overview</i>	11.2.4	624
10.5.2	<i>Lagrange Multiplier Method</i>	11.3.5	624
10.5.3	<i>Assembly of Interface Matrix</i>	11.3.5	629
10.5.4	<i>Lagrange Multipliers for Small-Displacement Elastostatics</i>	11.3.5	629
10.5.5	<i>Penalty Method for Nonlinear Frictionless Contact</i>	11.3.5	630
10.5.6	<i>Penalty Method for Small-Displacement Elastostatics</i>	11.3.5	631
10.5.7	<i>Augmented Lagrangian</i>	11.3.4	631
10.5.8	<i>Perturbed Lagrangian</i>	11.3.4	633
10.5.9	<i>Regularization</i>	11.3.4	637
10.6	<b>On Explicit Methods</b>	11.2.4	638
10.6.1	<i>Explicit Methods</i>	11.2.4	638
10.6.2	<i>Contact in One Dimension</i>	12.2.6	639
10.6.3	<i>Penalty Method</i>	12.2.1	641
10.6.4	<i>Explicit Algorithm</i>	12.2.3	642
<b>11</b>	<b>EXtended Finite Element Method (XFEM)</b>	12.2.4	643
11.1	<b>Introduction</b>	12.2.4	643
11.1.1	<i>Strong Discontinuity</i>	12.2.4	643
11.1.2	<i>Weak Discontinuity</i>	12.2.4	645
11.1.3	<i>XFEM for Discontinuities</i>	12.2.4	646
11.2	<b>Partition of Unity and Enrichments</b>	12.2.4	647
11.3	<b>One-Dimensional XFEM</b>	12.2.4	648
11.3.1	<i>Strong Discontinuity</i>	12.2.4	648
11.3.2	<i>Weak Discontinuity</i>	12.2.3	652
11.3.3	<i>Mass Matrix</i>	12.2.3	655
11.4	<b>Multi-Dimension XFEM</b>	12.2.4	656
11.4.1	<i>Crack Modeling</i>	12.2.4	656

11.4.2	<i>Tip Enrichment</i>	658
11.4.3	<i>Enrichment in a Local Coordinate System</i>	660
11.5	Weak and Strong Forms	660
11.6	Discrete Equations	662
11.6.1	<i>Strain–Displacement Matrix for Weak Discontinuity</i>	665
11.7	Level Set Method	668
11.7.1	<i>Level Set in 1D</i>	668
11.7.2	<i>Level Set in 2D</i>	668
11.7.3	<i>Dynamic Fracture Growth Using Level Set Updates</i>	669
11.8	The Phantom Node Method	670
11.8.1	<i>Element Decomposition in 1D</i>	670
11.8.2	<i>Element Decomposition in Multi-Dimensions</i>	671
11.9	Integration	673
11.9.1	<i>Integration for Discontinuous Enrichments</i>	673
11.9.2	<i>Integration for Singular Enrichments</i>	675
11.10	An Example of XFEM Simulation	675
11.11	Exercise	678
<b>12</b>	<b>Introduction to Multiresolution Theory</b>	<b>681</b>
12.1	Motivation: Materials are Structured Continua	681
12.2	Bulk Deformation of Microstructured Continua	685
12.3	Generalizing Mechanics to Bulk Microstructured Continua	686
12.3.1	<i>The Need for a Generalized Mechanics</i>	686
12.3.2	<i>Major Ideas for a Generalized Mechanics</i>	687
12.3.3	<i>Higher-Order Approach</i>	688
12.3.4	<i>Higher-Grade Approach</i>	689
12.3.5	<i>Reinterpretation of Micromorphism for Bulk Microstructured Materials</i>	691
12.4	Multiscale Microstructures and the Multiresolution Continuum Theory	696
12.5	Governing Equations for MCT	699
12.5.1	<i>Virtual Internal Power</i>	699
12.5.2	<i>Virtual External Power</i>	699
12.5.3	<i>Virtual Kinetic Power</i>	700
12.5.4	<i>Strong Form of MCT Equations</i>	700
12.6	Constructing MCT Constitutive Relationships	701
12.7	Basic Guidelines for RVE Modeling	705
12.7.1	<i>Determining RVE Cell Size</i>	706
12.7.2	<i>RVE Boundary Conditions</i>	707
12.8	Finite Element Implementation of MCT	710
12.9	Numerical Example	712
12.9.1	<i>Void-Sheet Mechanism in High-Strength Alloy</i>	712
12.9.2	<i>MCT Multiscale Constitutive Modeling Outline</i>	713
12.9.3	<i>Finite Element Problem Setup for a Two-Dimensional Tensile Specimen</i>	714
12.9.4	<i>Results</i>	716
12.10	Future Research Directions of MCT Modeling	718
12.11	Exercises	719

<b>13 Single-Crystal Plasticity</b>	<b>721</b>
13.1 Introduction	721
13.2 Crystallographic Description of Cubic and Non-Cubic Crystals	723
13.2.1 <i>Specifying Directions</i>	724
13.2.2 <i>Specifying Planes</i>	725
13.3 Atomic Origins of Plasticity and the Burgers Vector in Single Crystals	726
13.4 Defining Slip Planes and Directions in General Single Crystals	729
13.5 Kinematics of Single Crystal Plasticity	735
13.5.1 <i>Relating the Intermediate Configuration to Crystalline Mechanics</i>	735
13.5.2 <i>Constitutive Definitions of the Plastic Parts of Deformation Rate and Spin</i>	737
13.5.3 <i>Simplification of the Kinematics by Restriction to Small Elastic Strain</i>	738
13.5.4 <i>Final Remarks</i>	739
13.6 Dislocation Density Evolution	740
13.7 Stress Required for Dislocation Motion	742
13.8 Stress Update in Rate-Dependent Single-Crystal Plasticity	743
13.8.1 <i>The Resolved Shear Stress</i>	743
13.8.2 <i>The Resolved Shear Stress Rate</i>	743
13.8.3 <i>Updating Resolved Shear Stress in Rate-Dependent Materials</i>	744
13.8.4 <i>Updating the Cauchy Stress</i>	745
13.8.5 <i>Adiabatic Temperature Update</i>	745
13.9 Algorithm for Rate-Dependent Dislocation-Density Based Crystal Plasticity	745
13.10 Numerical Example: Localized Shear and Inhomogeneous Deformation	747
13.11 Exercises	750
<b>Appendix 1 Voigt Notation</b>	<b>751</b>
<b>Appendix 2 Norms</b>	<b>757</b>
<b>Appendix 3 Element Shape Functions</b>	<b>761</b>
<b>Appendix 4 Euler Angles From Pole Figures</b>	<b>767</b>
<b>Appendix 5 Example of Dislocation-Density Evolutionary Equations</b>	<b>771</b>
<b>Glossary</b>	<b>777</b>
<b>References</b>	<b>781</b>
<b>Index</b>	<b>795</b>