

Contents

1	Introduction.....	6
2	Initial state of the art analysis	7
2.1	Motion planning.....	7
2.2	Motion planning frameworks.....	8
2.2.1	Movelt!	8
2.2.2	Descartes	8
2.3	Perception	8
2.3.1	RGB-D sensors	8
2.3.2	Environment representation	9
2.3.3	Sensor data fusion	9
2.4	Analysis conclusion.....	9
3	Investigating performance of Movelt! framework	10
3.1	Benchmark of parameters.....	10
3.1.1	Tested parameters	10
3.1.2	Measured indicators.....	10
3.1.3	Evaluation of benchmark results.....	11
3.2	Optimisation of parameter settings	12
3.2.1	Selecting parameters for optimisation.....	12
3.2.2	Benchmarks of optimised parameters	12
3.2.3	Optimisation results evaluation	12
3.3	Conclusion	12
4	Improving human awareness during robot-human collaboration.....	13
4.1	Graphical feedback.....	13
4.1.1	Light projectors.....	13
4.1.2	Augmented and Mixed Reality approaches	14
4.2	Acoustic feedback.....	14
4.3	Haptic feedback.....	14
4.4	Conclusion of the analysis	14
5	Haptic feedback devices	15
5.1	Actuation	15
5.2	Placement.....	15
5.2.1	Hand	15
5.2.2	Wrist	15
5.2.3	Forearm	15
5.3	Feedback implementation.....	15

5.4	Analysis conclusion.....	15
6	Aims and objectives of the dissertation thesis.....	16
7	Implementation of improved human-robot collaboration	17
7.1	Principle.....	17
7.1.1	Simultaneous motor activation mode.....	18
7.1.2	Directional motor activation mode	19
7.2	Experimental workplace.....	19
7.3	Haptic HMI device	19
7.3.1	Tactors locations	20
7.3.2	HMI controller software	20
7.4	PC-side software.....	20
7.4.1	ROS HMI Tracker	21
7.4.2	ROS HMI Controller	22
7.4.3	ROS Task Commander	24
7.4.4	ROS Workspace model	24
7.4.5	ROS MoveIt!	25
7.4.6	Additional ROS vizualization in RViz	27
8	Initial testing of the system.....	28
9	HMI usability experiment.....	30
9.1	Experiment description	30
9.1.1	Case study.....	30
9.1.2	Hypotheses	31
9.1.3	Methodology	31
9.2	Experiment results evaluation.....	32
9.2.1	Objective evaluation.....	32
9.2.2	Subjective evaluation	33
9.2.3	Experiment conclusion	34
10	Conclusions.....	35
10.1	Contribution for scientific discipline	36
10.2	Contribution for practice.....	36
10.3	Recommendation for further research	36
11	References.....	38
12	Publications	39
13	Appendixes	40