

CONTENTS

1. INTRODUCTION	1
2. THE DIFFERENTIAL ANALYSER	4
2.1. The Nature of the Problem of Instrumental Solution of Differential Equations	4
2.2. Integrating Mechanisms	5
2.3. The General Idea of the Differential Analyser	6
2.4. General Structure of the Earlier Forms of Differential Analyser	8
2.5. A New Differential Analyser	14
2.6. Using the Differential Analyser	17
2.7. Regenerative Connections	20
2.8. Automatic Generation of Any Function	21
2.9. Other Forms of Differential Analyser	23
2.10. Boundary Conditions in Numerical and Mechanical Integration of Differential Equations	24
2.11. Applications	25
3. THE DIFFERENTIAL ANALYSER AND PARTIAL DIFFERENTIAL EQUATIONS	26
3.1. Introduction	26
3.2. Replacement of the t -Derivative by a Finite Difference	27
3.3. Replacement of the x -Derivative by Finite Differences	28
3.4. Discussion of the Two Methods	30
3.5. Examples of Application to Equations of "Parabolic" Type	34
3.6. Hyperbolic Equations	37
3.7. Use of "Characteristics"	38
3.8. Another Application of Characteristics	41
4. SOME OTHER INSTRUMENTS	44
4.1. Introduction	44
4.2. Solution of Simultaneous Linear Algebraic Equations	44
4.3. The Isograph	46
4.4. Fourier Synthesisers	47
4.5. Integrating Instruments	48
4.6. Directors	52

5. INTRODUCTION TO LARGE AUTOMATIC DIGITAL MACHINES	54
5.1. Historical	55
5.2. Structure and Function in Calculating Machines	56
5.3. Functions to Be Provided in an Automatic Digital Machine	56
5.4. Representation of Numbers in the Machine	59
5.5. Arithmetical Operations	61
5.6. Serial (Successive) and Parallel (Simultaneous) Operations	65
5.7. Static and Dynamic Storage	66
5.8. Control and the Form of the Operating Instructions	67
6. CHARLES BABBAGE AND THE ANALYTICAL ENGINE	69
6.1. Babbage's Calculating Engines	69
6.2. Babbage's Analytical Engine	70
6.3. Control in the Analytical Engine	71
6.4. Organization of Calculations for the Analytical Engine	72
7. THE FIRST STAGE OF DEVELOPMENT	74
7.1. The Harvard Mark I Calculator	74
7.2. Control in the Harvard Mark I Machine	79
7.3. Relay Machines	80
7.4. The Eniac	81
7.5. Control in the Eniac	83
7.6. Centralised Control System of the Eniac	87
7.7. The I.B.M. Selective Sequence Electronic Calculator	87
7.8. An Application of the Eniac	88
7.9. The "Machine's-Eye View" in Programming a Calculation	92
8. PROJECTS AND PROSPECTS	94
8.1. The Main Directions of Development	94
8.2. Storage Systems	94
8.3. Serial Machines Using Delay-Line Storage	97
8.4. Functional Analysis of Serial Machines	97
8.5. Arithmetical Operation	103
8.6. Control	106
8.7. Parallel Machines	109
8.8. Other Types of Machine	111
8.9. Programming and Coding	111

9. HIGH-SPEED AUTOMATIC DIGITAL MACHINES AND NUMERICAL	
ANALYSIS	115
9.1. Introduction	115
9.2. Iterative Methods	116
9.3. Simultaneous Algebraic Equations	119
9.4. Solution of Ordinary Differential Equations	122
9.5. Solution of Ordinary Differential Equations with One-Point Boundary Conditions	123
9.6. Solution of Ordinary Differential Equations with Two-Point Boundary Conditions	125
9.7. Partial Differential Equations	127
REFERENCES	131
NAME INDEX	135
SUBJECT INDEX	136